

Akshay Raj Dhamija.me

Computer Vision & Deep Learning Researcher

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Experience

9/18 - Today

09/15 - 05/18 **Research Assistant**

[Vision And Security Technology Lab](#)

Working on various projects aimed at problems of image classification, object detections and face recognition. Focused on proposing solutions to improve performance both in traditional research based on closed set scenarios and real world or open set scenarios.

06/18 - 8/18

Computer Vision Intern

[Misty Robotics](#)

Developing object detection algorithms for systems with limited computational power. Formulating new evaluation metrics for comparing algorithms in unconstrained scenarios.

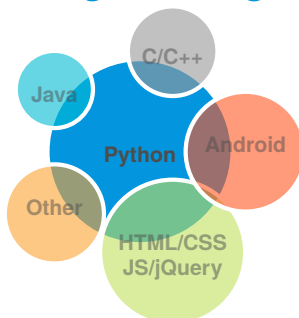
11/12 - 08/15

Project Consultant

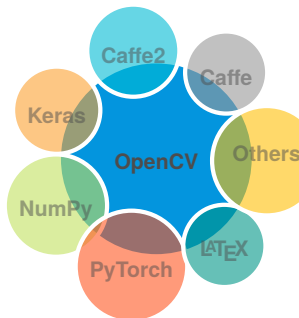
[My Personal Health Records eXpress \(MphRx\)](#)

An exhilarating experience, that exposed me to the dynamics of startups and healthcare industry while juggling various responsibilities such as project management, product design, requirement gathering, product delivery and market analysis. Restructured and launched products for various major hospitals and diagnostic chains in India and US.

Programming



Tools



Publications

Reducing Network Agnostophobia [link](#)

Akshay Raj Dhamija, Manuel Günther and Terrance E. Boulton

Neural Information Processing Systems (NeurIPS) 2018 - Spotlight Presentation

Improving Deep Network Robustness to Unknown Inputs with Objectosphere [link](#)

Akshay Raj Dhamija, Manuel Günther and Terrance E. Boulton

Uncertainty and Robustness in Deep Visual Learning (CVPR'2019 workshop) - Spotlight

Learning and the Unknown: Surveying Steps toward Open World Recognition [link](#)

Terrance E. Boulton, **Akshay Raj Dhamija**, Steve Cruz, Manuel Günther, James Henrydoss and Walter Scheirer

Proceedings of the AAAI Conference on Artificial Intelligence - 2019

Unconstrained face detection & open-set face recognition challenge [link](#) [website](#)

M. Günther, P. Hu, C. Herrmann, C. H. Chan, M. Jiang, S. Yang, **A. R. Dhamija**, D. Ramanan, J. Beyerer, J. Kittler, M. Al Jazaery, M. I. Nouyed, G. Guo, C. Stankiewicz, and T. E. Boulton

Challenge paper at International Joint Conference on Biometrics (IJCB) 2017

What's hiding in my deep features? [link](#)

Ethan M. Rudd, Manuel Günther, **Akshay R. Dhamija**, Faris A. Kateb and Terrance E. Boulton
Book chapter - Deep Learning in Biometrics By CRC/Taylor & Francis Press.

Openset: The overlooked elephant of object detection [Under Review](#)

Akshay R. Dhamija, Manuel Günther, Jonathan Ventura and Terrance E. Boulton

Awards

Top Scholar Award - Mountain Lion Research Day

University of Colorado

Outstanding Masters Degree Student - Computer Science

University of Colorado

Education

2018 - Now **PhD Student (Advisor Dr. Terrance E. Boult) - Computer Science**

[University of Colorado, Colorado Springs](#)

2015 - 2017 **Master of Science - Computer Science**

[University of Colorado, Colorado Springs](#)

2010 - 2012 **Master of Business Administration - Software Enterprise Management**

[Guru Gobind Singh Indraprastha University, New Delhi](#)

2006 - 2010 **Bachelor of Technology - Biomedical Engineering**

[Rajasthan Technical University, Kota, Rajasthan](#)

Other Projects

Feature extraction & point cloud reconstruction – Satellite images

Under the guidance of Dr. Jonathan Ventura, this project aims at feature detection from satellite images as well as point cloud construction from multi-view satellite imagery using deep neural networks.

VR website using A-Frame

Aimed towards experiencing basics of Virtual Reality and creating a personal virtual reality website using A-Frame. The website may be found at dhamija.me/vr

Android application for GRE aspirants

The project was aimed at learning Android Application development and creating an application for GRE aspirants for practicing Reading Comprehensions. More than 4000 Downloads and 900 active users. [Play Store Link](#)

Robot object fetching

The project was a part of the robotics course at UCCS, where a robot equipped with a camera and a raspberry pie was used to identify a predefined cylindrical object, approach it and grip. Four ultra-sonic sensors were also used in order to localize the robot. ROS was used in the above project.

Patient monitoring system

Implementing goods codification and production reporting system at FPSI

Proposing facility layout plans for an industry in MSME segment